



MEDNARODNA
PODDIPLOMSKA ŠOLA
JOŽEFA STEFANA

JOŽEF STEFAN
INTERNATIONAL
POSTGRADUATE SCHOOL

Meshless Adaptive Solution Procedure for Efficient Solving of Partial Differential Equations

Mitja Jančič

Ljubljana, November 16, 2023

Table of Contents

1. Motivation
2. Monomial Augmentation Guidelines
3. hp -adaptive Solution Procedure
4. Spatially-Adaptive Approximation Methods
5. Conclusions

Seminar III:

Seminar III at the doctoral level is intended to present the research or project results of the studies. Students prepare a comprehensive presentation of their results and present their seminars in front of a committee of three professors.



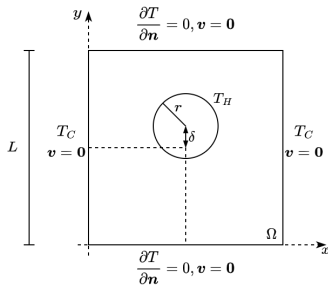
Numerical Treatment of PDEs

1. Domain discretization
2. Differential operator approximation
3. PDE discretization
4. Solve sparse linear system

Meshless approximation:

$$(\mathcal{L}u)(\mathbf{x}_c) \approx \sum_{i=1}^n w_i u(\mathbf{x}_i)$$
$$\mathcal{L} \Big|_{\mathbf{x}_c} = \mathbf{w} \mathcal{L}(\mathbf{x}_c)^T$$

Example convection-driven fluid flow problem:



$$\nabla \cdot \vec{v} = 0,$$

$$\frac{\partial \vec{v}}{\partial t} + \vec{v} \cdot \nabla \vec{v} = -\nabla p + \nabla \cdot (Ra \nabla \vec{v}) - \vec{g} Ra Pr T_{\Delta},$$

$$\frac{\partial T}{\partial t} + \vec{v} \cdot \nabla T = \nabla \cdot (\nabla T)$$

Approximation Methods

- ▶ **Radial Basis Function-generated Finite Differences (RBF-FD)**
 - ▶ Polyharmonic Splines augmented with monomials
 - ▶ Relatively large support size $n = \binom{m+d}{d}$.
- ▶ **Diffuse Approximation Method (DAM)**
 - ▶ Referred to as Weighted Least Squares (WLS) method
 - ▶ Only monomials (less basis functions)
 - ▶ Relatively large support size $n = \binom{m+d}{d}$
- ▶ **The simplest collocation form (MON)**
 - ▶ Monomials
 - ▶ Small support size $n = 5$ in 2D and $n = 7$ in 3D.
 - ▶ Stable only on regular nodes

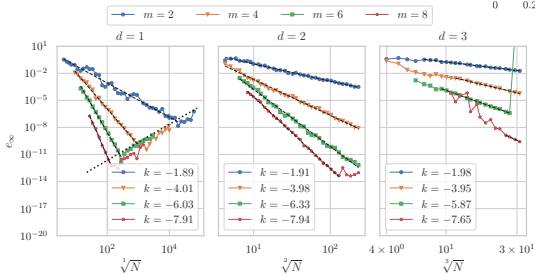
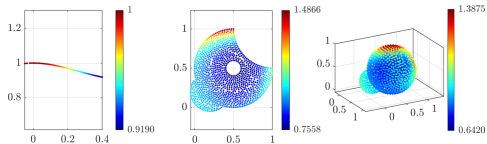
Monomial Augmentation: Problem Setup

Numerical solution u_h of Poisson's equation with both Dirichlet and Neumann boundary conditions is studied:

$$\nabla^2 u(\mathbf{x}) = f_{lap}(\mathbf{x}) \quad \text{in } \Omega, \quad (1)$$

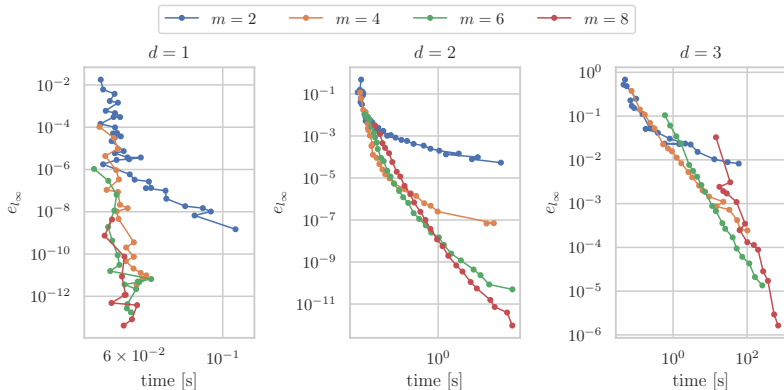
$$u(\mathbf{x}) = f(\mathbf{x}) \quad \text{on } \Gamma_d, \quad (2)$$

$$\nabla u(\mathbf{x}) = \mathbf{f}_{grad}(\mathbf{x}) \quad \text{on } \Gamma_n. \quad (3)$$



- ▶ Approximation order controlled with the highest order of augmenting monomial.
- ▶ Note: recommended stencil size $n = \binom{m+d}{d}$

Monomial Augmentation: Time vs. Error



The recommended augmentation order

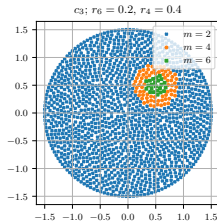
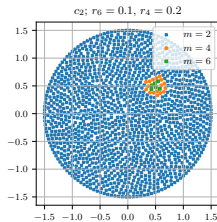
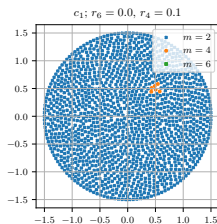
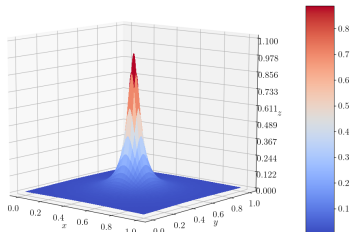
$$m = \frac{5}{4}k + \frac{4}{5}d - 2$$

p -refinement

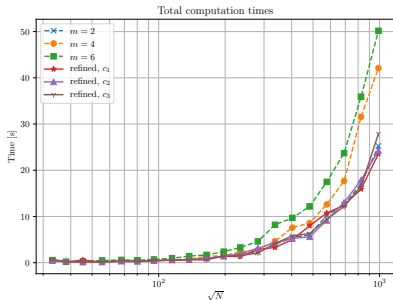
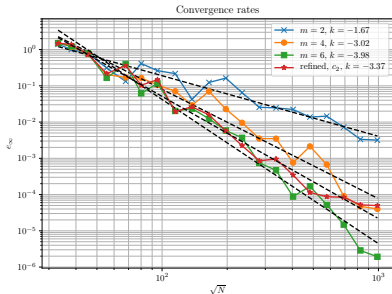
Poisson problem with strong source in the domain

$$\nabla^2 u(\mathbf{x}) = f_{\text{lap}}(\mathbf{x})$$

$$f_{\text{lap}}(\mathbf{x}) = 3200 \frac{25 \|4\mathbf{x} - 2\|^2}{f(\mathbf{x})^3} - 800 \frac{d}{f(\mathbf{x})}$$

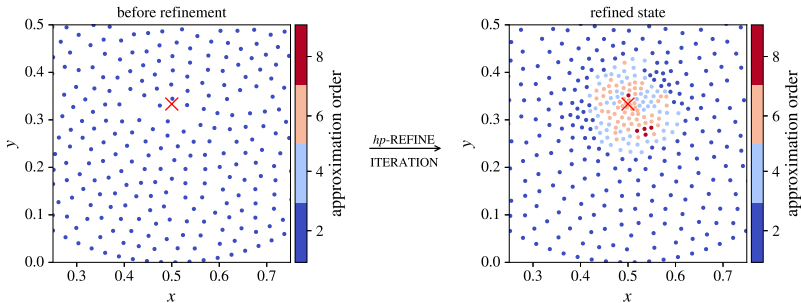


ρ -refinement: Results



Computational time can be reduced by approximately 50 %. At the same time, accuracy of the numerical solution is notably better compared to unrefined solutions (at second order approximation).

hp-refinement: Goal



Workflow

Based on the well established **solve-estimate-mark-refine** paradigm.

hp-refinement: **solve-estimate-mark-refine**

Poisson problem with exponentially strong source in the domain

$$\nabla^2 u(\mathbf{x}) = 2ae^{-a\|\mathbf{x}-\mathbf{x}_s\|^2} (2a\|\mathbf{x}-\mathbf{x}_s\| - d) \quad \text{in } \Omega,$$

$$u(\mathbf{x}) = e^{-a\|\mathbf{x}-\mathbf{x}_s\|^2} \quad \text{on } \Gamma_d,$$

$$\nabla u(\mathbf{x}) = -2a(\mathbf{x}-\mathbf{x}_s)e^{-a\|\mathbf{x}-\mathbf{x}_s\|^2} \quad \text{on } \Gamma_n$$

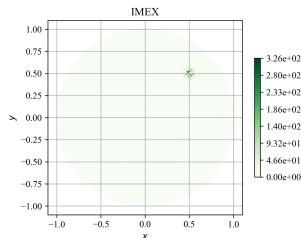
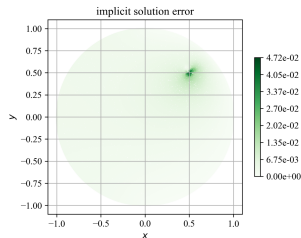
Setup

- ▶ RBF-FD
- ▶ PHS order $k = 3$
- ▶ Monomial augmentation with $m \in \{2, 4, 6, 8\}$
- ▶ IMEX with monomials $m \in \{4, 6, 8, 10\}$

hp-refinement: solve-estimate-mark-refine

Consider a problem of type $\mathcal{L}u = f_{RHS}$.
The IMplicit-EXPLICIT error indicator:

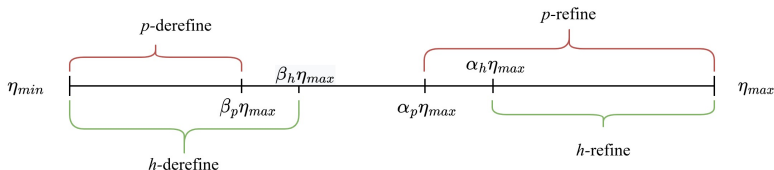
1. Obtain implicit solution $u^{(im)}$ to governing problem using low-order approximations of \mathcal{L} , i.e. $\mathcal{L}_{(im)}^{(lo)}$.
2. Obtain high-order approximations of explicit operators \mathcal{L} , i.e. $\mathcal{L}_{(ex)}^{(hi)}$.
3. Apply $\mathcal{L}_{(ex)}^{(hi)}$ to $u^{(im)}$ and obtain $f_{(ex)}$ in the process
4. Compare f_{RHS} and $f_{(ex)}$



hp-refinement: solve-estimate-mark-refine

The modified Texas Three-Fold strategy for error indicator field η

$$\begin{cases} \eta_i > \alpha\eta_{max}, & \text{refine} \\ \beta\eta_{max} \leq \eta_i \leq \alpha\eta_{max}, & \text{do nothing.} \\ \eta_i < \beta\eta_{max}, & \text{derefine} \end{cases}$$



Advantage

Easy to understand and implement.

Problem

Does not lead to optimal results.

hp-refinement: solve-estimate-mark-refine

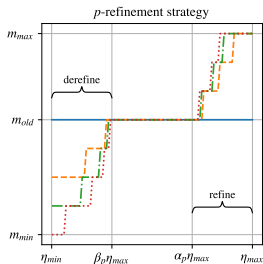
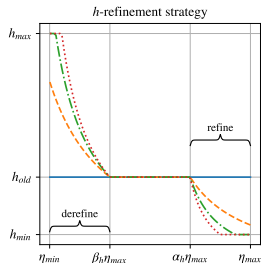
Defining the amount of (de)refinement.

h-refine

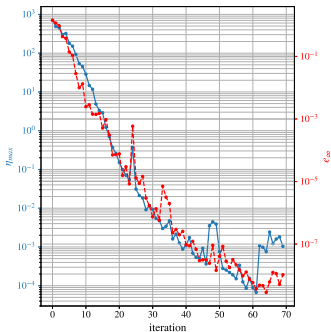
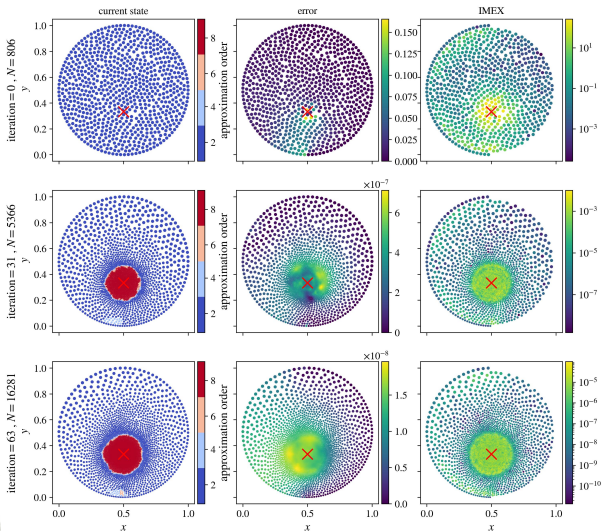
$$h_i^{\text{new}}(\mathbf{p}) = \frac{h_i^{\text{old}}}{\frac{\eta_j - \alpha \eta_{\max}}{\eta_{\max} - \alpha \eta_{\max}} (\lambda - 1) + 1}$$

h-derefine

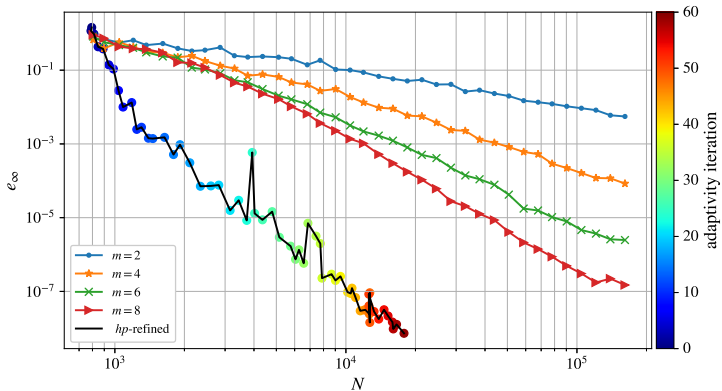
$$h_i^{\text{new}}(\mathbf{p}) = \frac{h_i^{\text{old}}}{\frac{\beta \eta_{\max} - \eta_j}{\beta \eta_{\max} - \eta_{\min}} \left(\frac{1}{\vartheta} - 1 \right) + 1}$$



hp-adaptivity: Poisson problem



hp-adaptivity: Convergence Rates



Setup

RBF-FD

PHS order $k = 3$

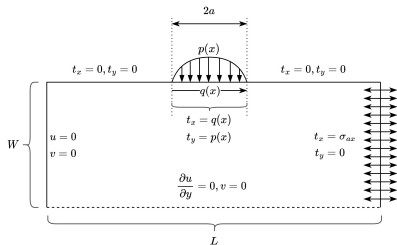
Monomial augmentation
with $m \in \{2, 4, 6, 8\}$

IMEX with monomials
 $m \in \{4, 6, 8, 10\}$

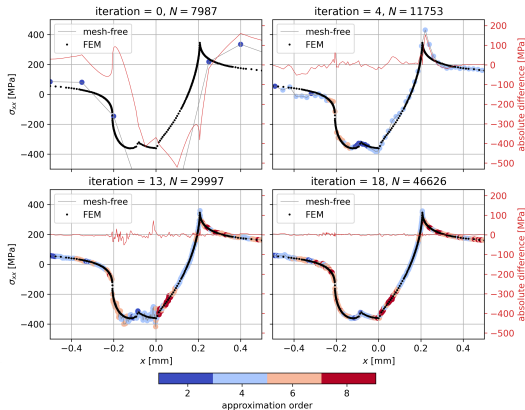
hp -adaptivity: Fretting Fatigue Problem

The problem is governed by the Cauchy-Navier equations

$$(\lambda + \mu)\nabla(\nabla \cdot \mathbf{u}) + \mu\nabla^2 \mathbf{u} = \mathbf{f}$$

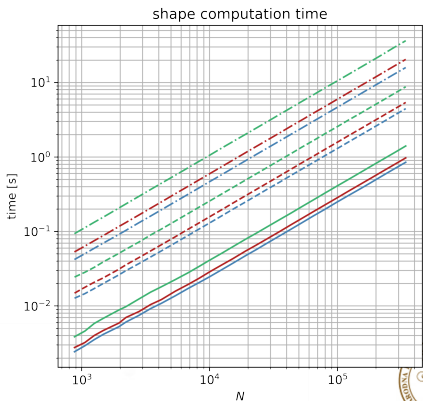
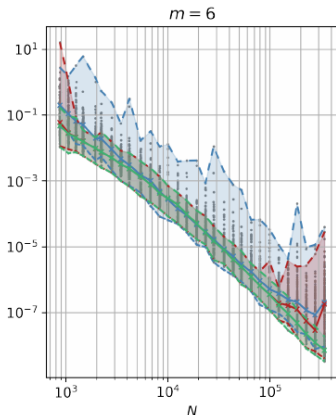
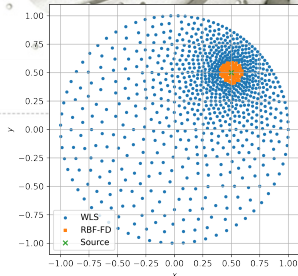


► Good agreement with FEM solution



Hybrid WLS-RBF-FD approximation

- ▶ Spatially-variable approximation method
- ▶ For greater solving efficiency: RBF-FD should be employed on as little nodes as possible



Hybrid scattered-regular

Discretization:

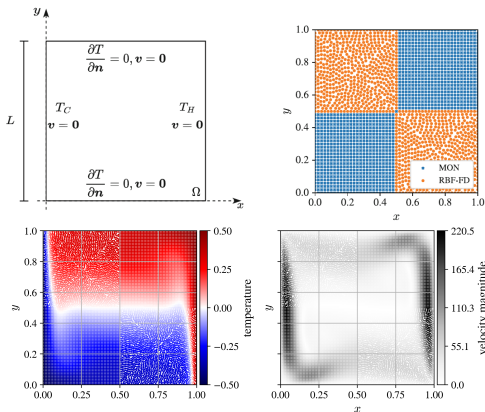
- ▶ Scattered nodes only where necessary
- ▶ Regular nodes elsewhere

Approximation:

- ▶ RBF-FD on scattered nodes ($n = 12$ in 2D for second order approximation)
- ▶ MON on regular nodes ($n = 5$ in 2D)

Note:

No special treatment required on the transition from scattered to regular nodes.



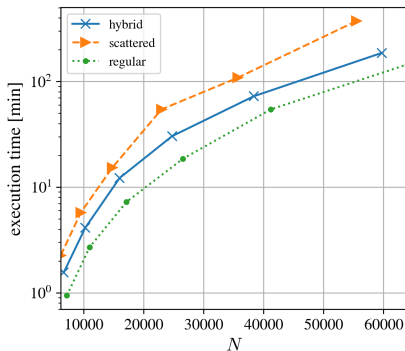
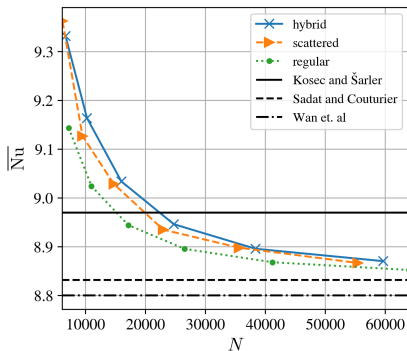
$$\frac{\partial \vec{v}}{\partial t} + \vec{v} \cdot \nabla \vec{v} = -\nabla p + \nabla \cdot (Ra \nabla \vec{v}) - \vec{g} Ra Pr T_{\Delta}$$

$$\frac{\partial T}{\partial t} + \vec{v} \cdot \nabla T = \nabla \cdot (\nabla T)$$

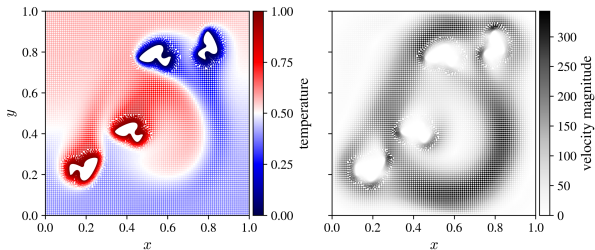
$$\nabla \cdot \vec{v} = 0$$

Hybrid scattered-regular: DVD convergence

Nusselt number $Nu = \frac{L}{T_H - T_C} \frac{\partial T}{\partial \mathbf{n}}$: the ratio between convective and conductive heat transfer (here computed along the cold wall).



Hybrid scattered-regular: Irregular domains

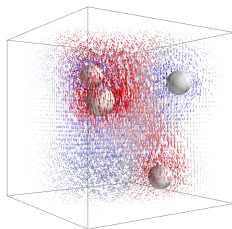
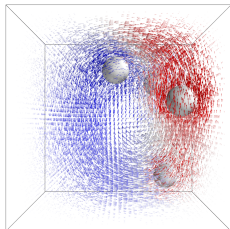
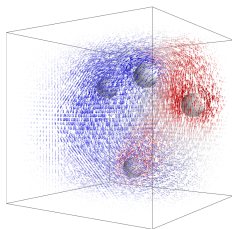


2D:

Approximation	\bar{Nu}	execution time [min]	N
scattered	12.32	46.31	10 534
hybrid	12.36	29.11	11 535

3D:

Approximation	\bar{Nu}	execution time [h]	N
scattered	7.36	48.12	65 526
hybrid	6.91	20.54	74 137



Summary

Presented:

- ▶ Monomial augmentation guidelines
- ▶ p -refinement
- ▶ hp -adaptive solution procedure
- ▶ Hybrid WLS–RBF–FD method
- ▶ Hybrid scattered-uniform discretization approach

Future work:

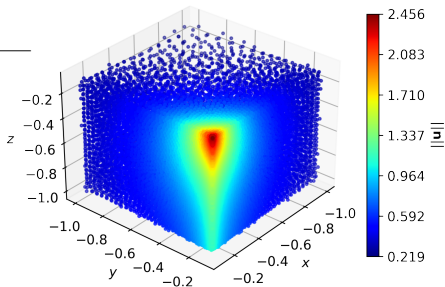
- ★ Different marking and refinement strategies employed by the hp -adaptive solution procedure
- ★ Different error indicators in the hp -adaptivity
- ★ hp -adaptivity in the context of fluid flow problems

Questions?

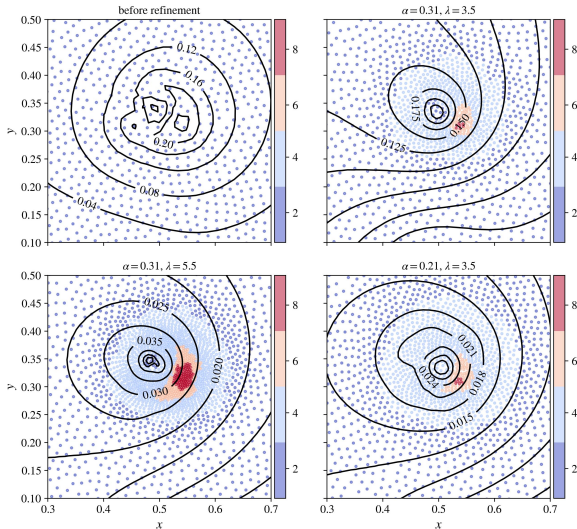
Hybrid WLS–RBF-FD approximation: 3D-Domain

Approximation	e_∞	t_{shape} [s]	$N_{\text{RBF-FD}}/N \cdot 100$
WLS	NaN	4.74	0.00
RBF-FD	$9.48 \cdot 10^{-5}$	8.22	100.00
hybrid	$2.37 \cdot 10^{-3}$	6.15	34.28

- ▶ RBF-FD part improves stability
- ▶ Shorter execution times observed
- ▶ Other combination of approximation method could be used



hp-adaptivity: Brief Study of Free Parameters



Setup

RBF-FD

PHS order $k = 3$

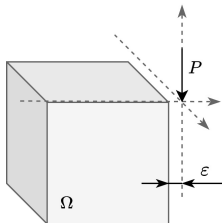
Monomial augmentation
with $m \in \{2, 4, 6, 8\}$

IMEX with monomials
 $m \in \{4, 6, 8, 10\}$

hp -adaptivity: Boussinesq's Problem

The problem is governed by the Cauchy-Navier equations

$$(\lambda + \mu)\nabla(\nabla \cdot \mathbf{u}) + \mu\nabla^2 \mathbf{u} = \mathbf{f}$$



- ▶ Good agreement with closed form solution
- + Avoided fine-tuning with free parameters

